The Magic Behind PREEMPT_RT

Haris Okanovic Senior Software Engineer National Instruments

(Original slides by Julia Cartwright)





What is a Real-Time Operating System (RTOS)?

What is PREEMPT_RT?

How does PREEMPT_RT make Linux real-time?



A *real-time system* is a system in which timing requirements are functional.

A real-time operating system (RTOS) manages system resources in a way that satisfies timing requirements of running application(s).

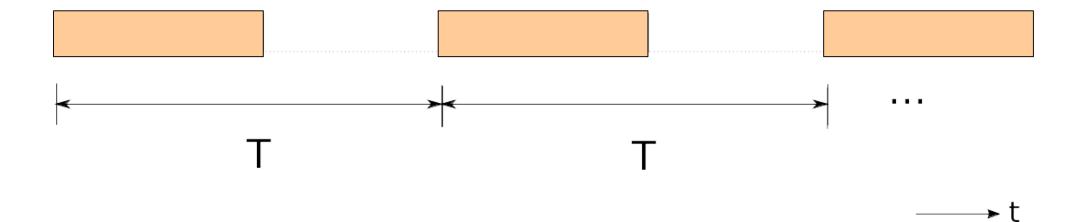


```
for (;;) {
   t0 = now();
   feedback = sample();
   output =
     calculate(feedback, setpoint);
   write new point(output);
   sleep until(t0 + T);
```



```
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   t0 = now();
   feedback = sample();
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     calculate(feedback, setpoint);
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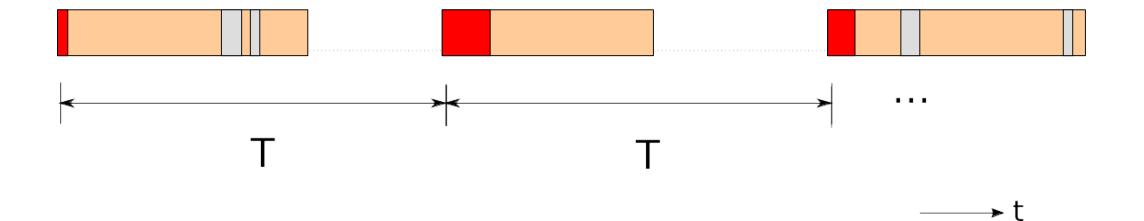




Wakeup latency (or scheduling latency) is the time between the firing of an external event and the execution of the relevant thread.

Execution latency is the difference between actual and ideal execution times.







Wakeup Test

```
for (;;) {
   t0 = now();
   sleep(expected T);
   t1 = now();
   actual T = t1 - t0;
   plot(actual T - expected T);
```

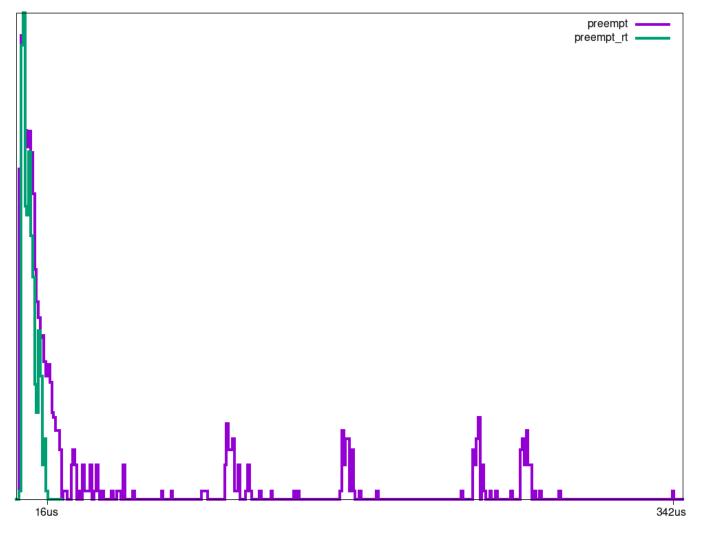


Wakeup Test

```
for (;;) {
   t0 = now();
   sleep(expected T);
   t1 = now();
   actual T = t1 - t0;
   plot(actual_T - expected T);
```



Wakeup Test





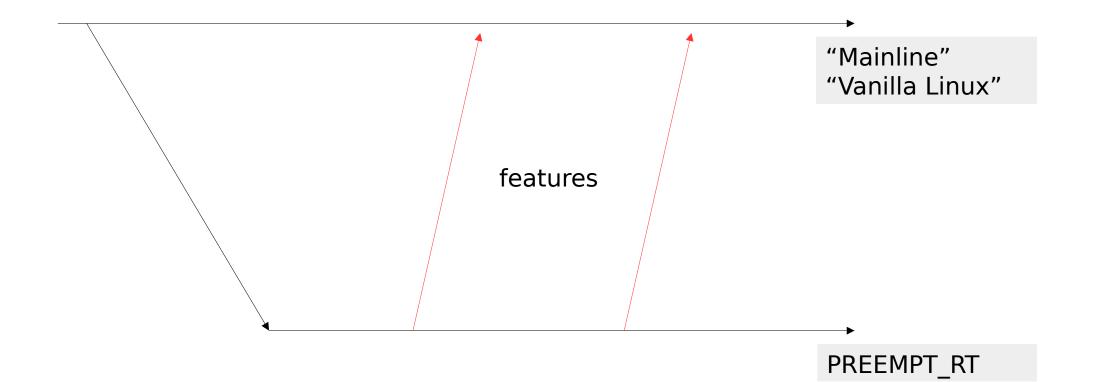
Cyclictest:

https://rt.wiki.kernel.org/index.php/Cyclictest
https://git.kernel.org/pub/scm/utils/rt-tests/rt-tests.git

E.g.

cyclictest -S -p 98 -m -h 350 --histfile=h.txt







https://wiki.linuxfoundation.org/realtime/

Coalition of numerous organizations and users

Mainline + test PREEMPT_RT patchset



https://www.suse.com/products/realtime

https://access.redhat.com/products/red-hat-enterprise-mrg-realtime

https://packages.debian.org/linux-image-rt

https://www.windriver.com/products/linux

https://www.mentor.com/embedded-software/linux

https://www.ni.com/nilinuxrt

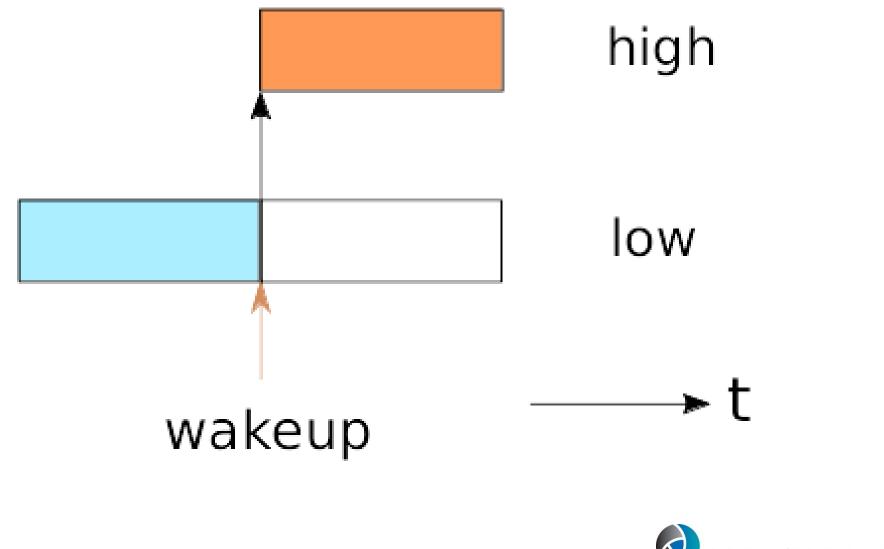


A thread is considered *preempted* when it's execution is suspended due to the wakeup and execution of a higher priority thread.

A thread is considered *preemptible* if the wakeup of a higher priority thread would trigger a preemption event.

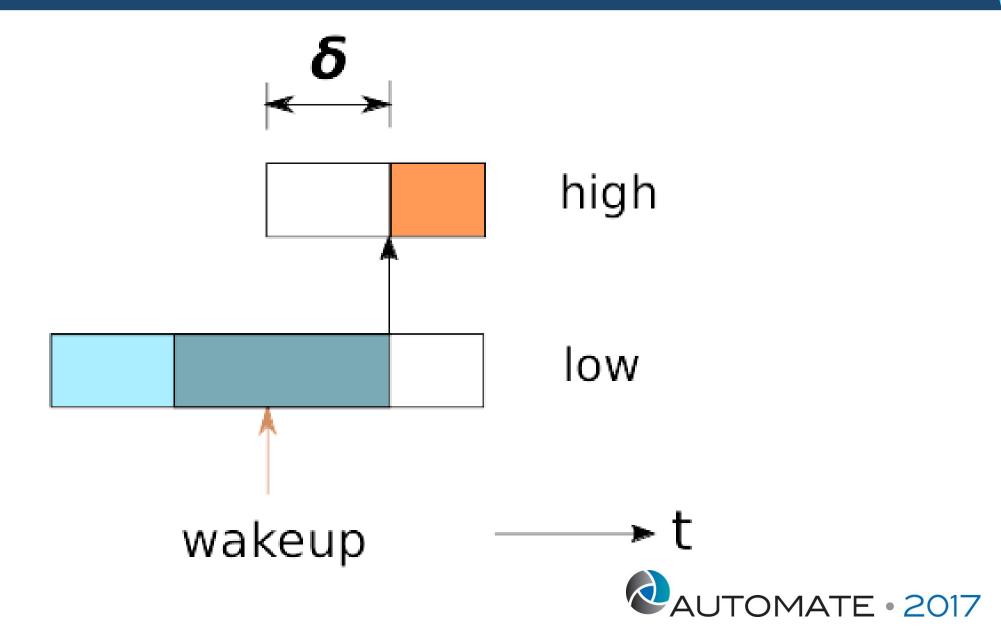


Preemption





Preemption



A *preemption model* defines, at compile time, which kernel code paths may be preempted.



Linux Preemption Model

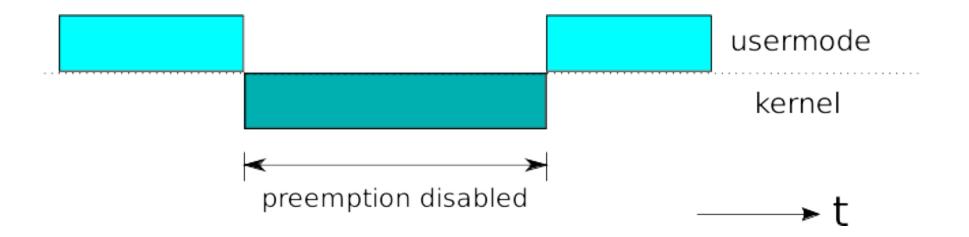
Vanilla

- PREEMPT_NONE
- PREEMPT_VOLUNTARY
- PREEMPT

RT Patch

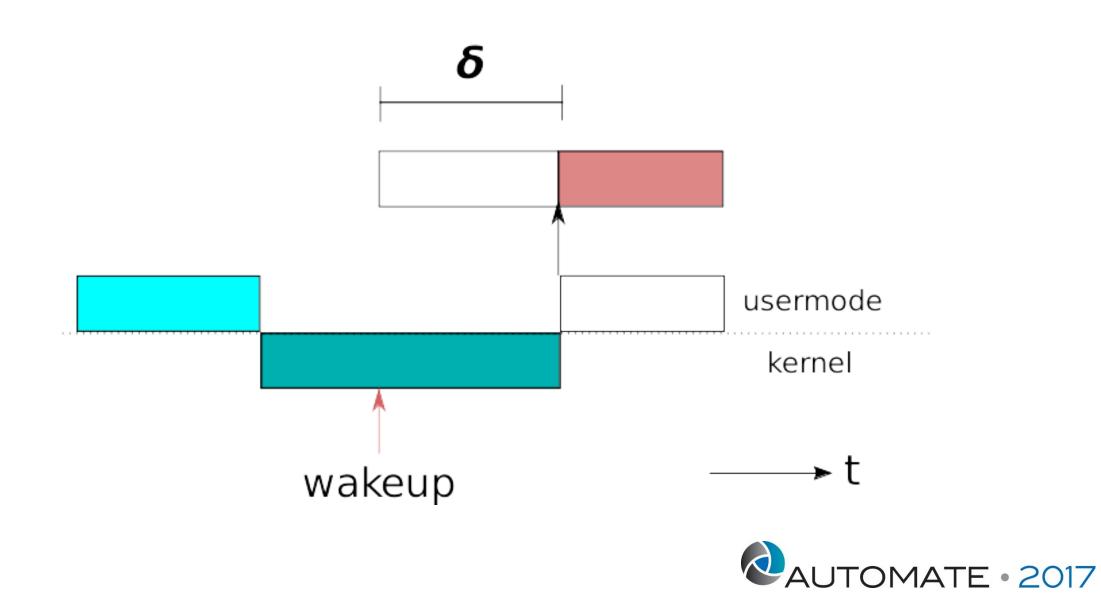
• PREEMPT_RT_FULL



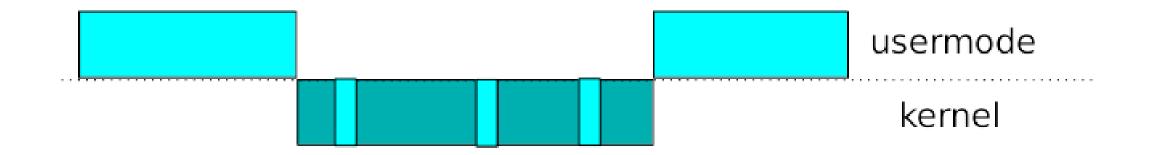




PREEMPT_NONE



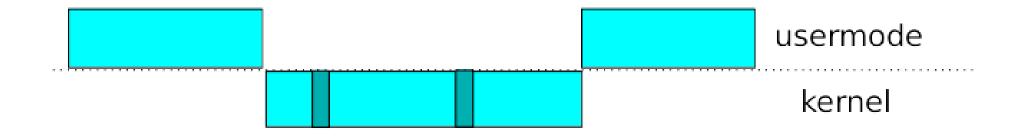
PREEMPT_VOLUNTARY







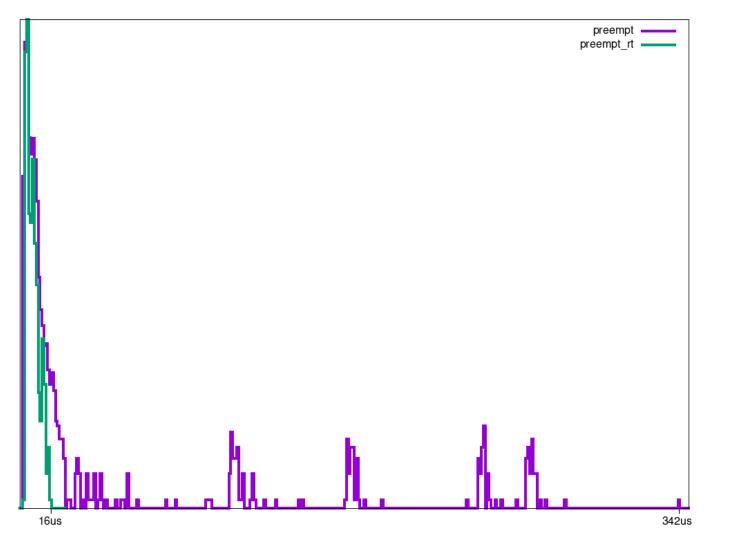








PREEMPT_RT Does Better



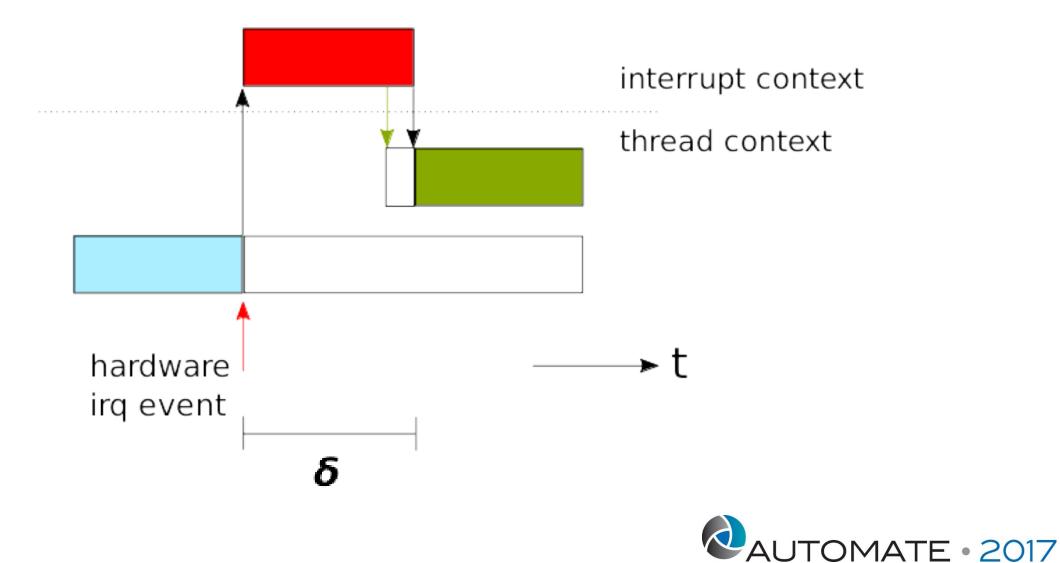


Thread context is any execution flow initiated by software.

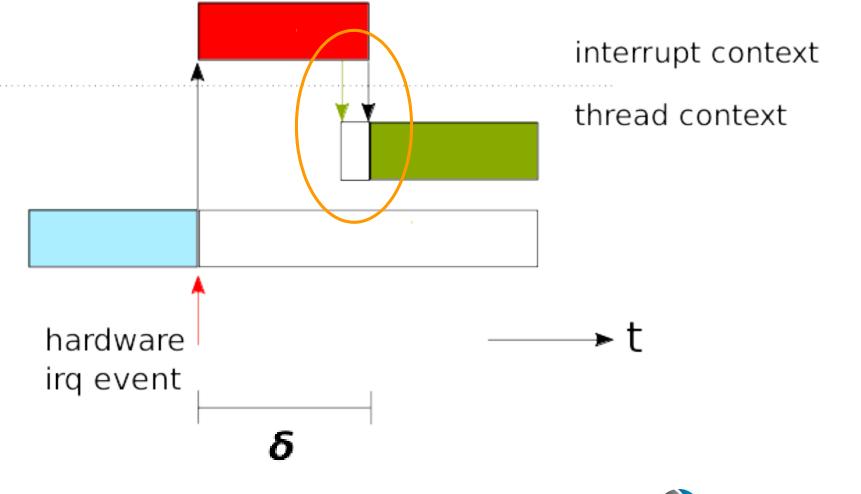
Interrupt context is any execution flow initiated by hardware.



E.g. IRQ Triggered Task Switch

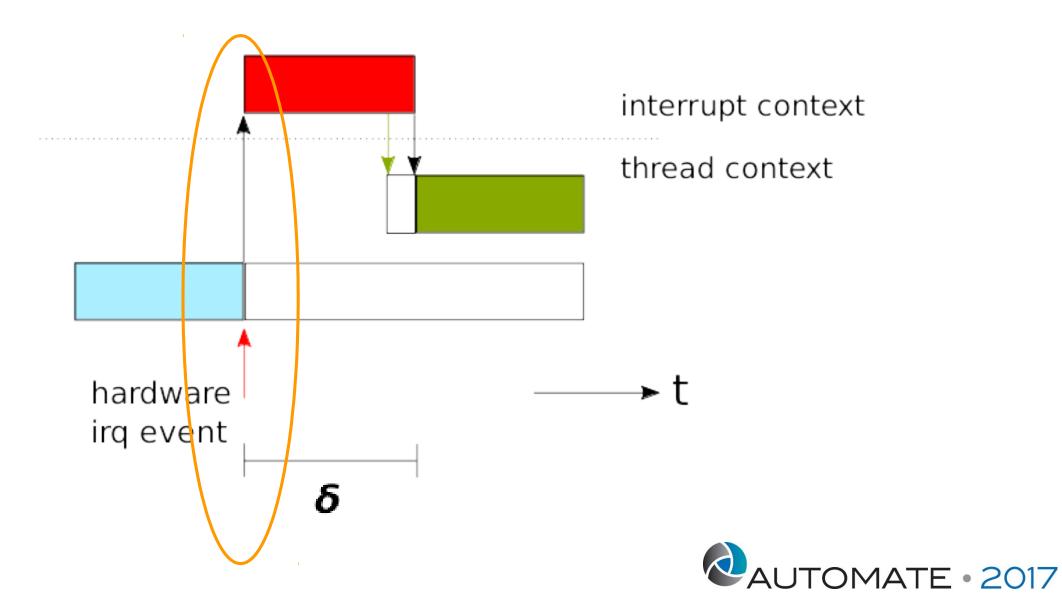


E.g. IRQ Triggered Task Switch

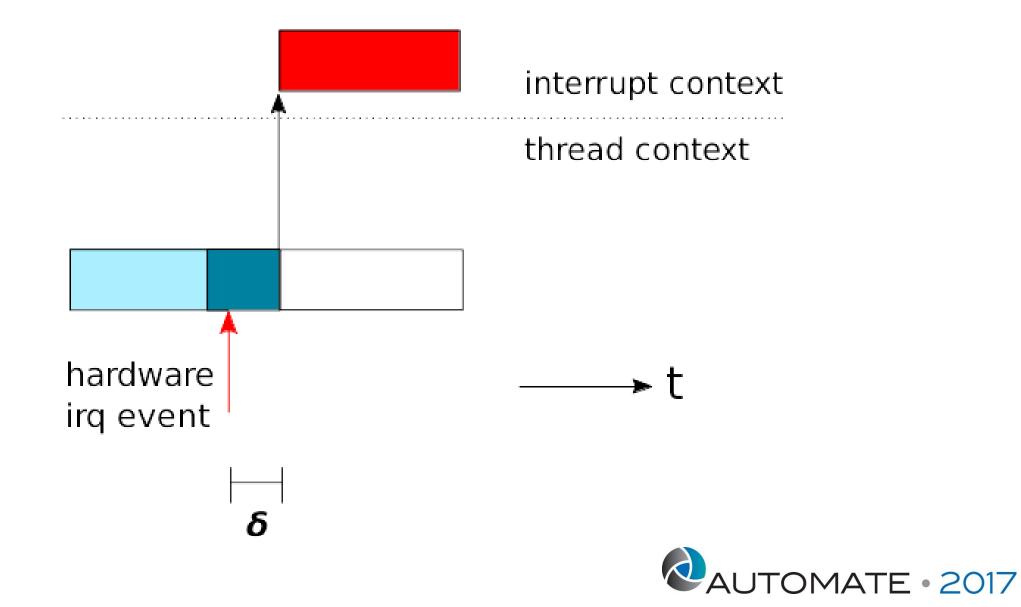




E.g. IRQ Triggered Task Switch



Interrupts Disabled

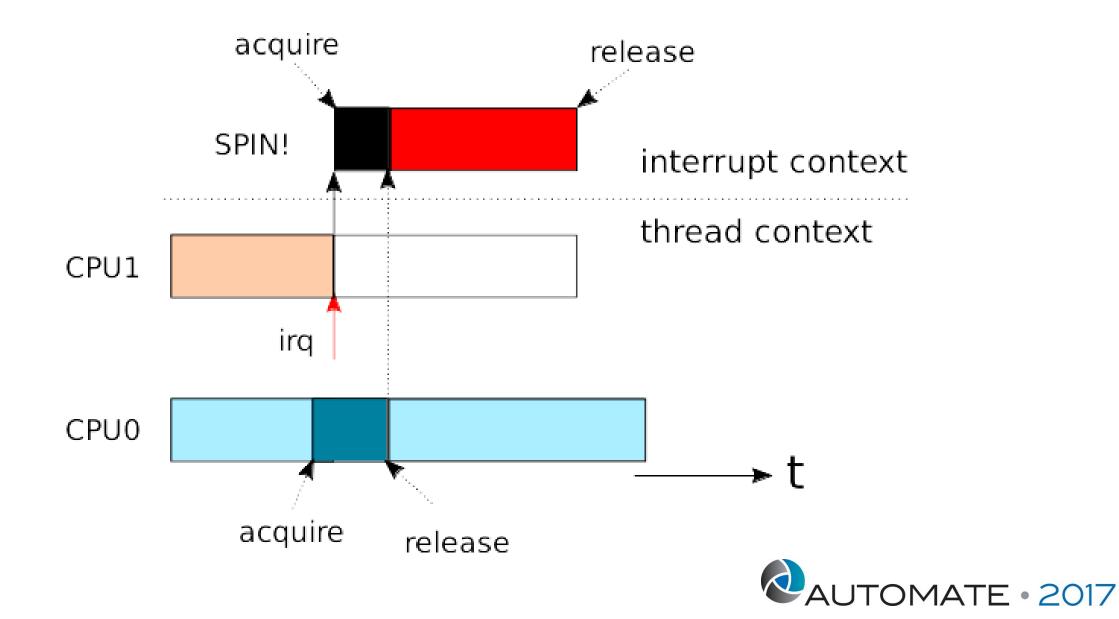


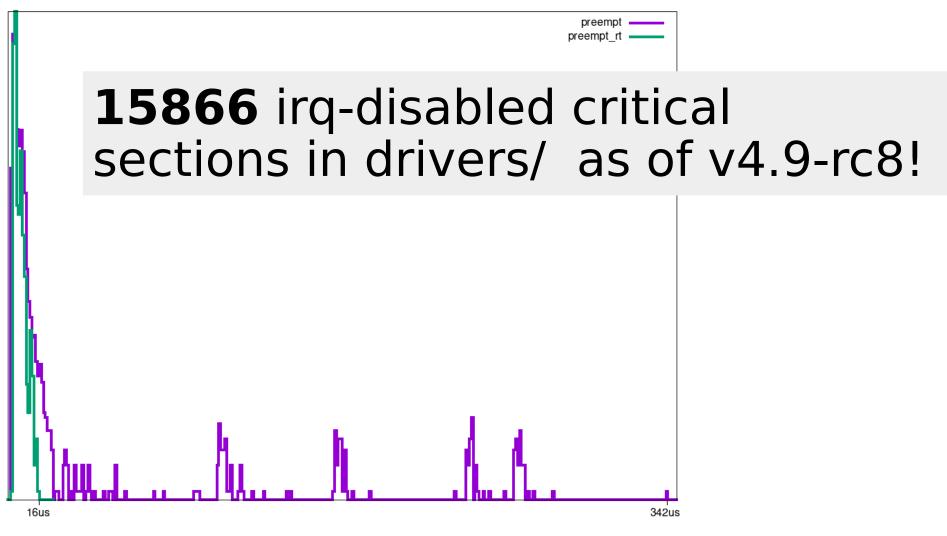
Interrupts Disabled

- Disable/enable interrupts:
 - local_irq_disable() / local_irq_enable()
- Spin lock/unlock
 - _spin_lock() / _spin_unlock()
- Spin lock/unlock + disable interrupts:
 - spin_lock_irq() / spin_unlock_irq()



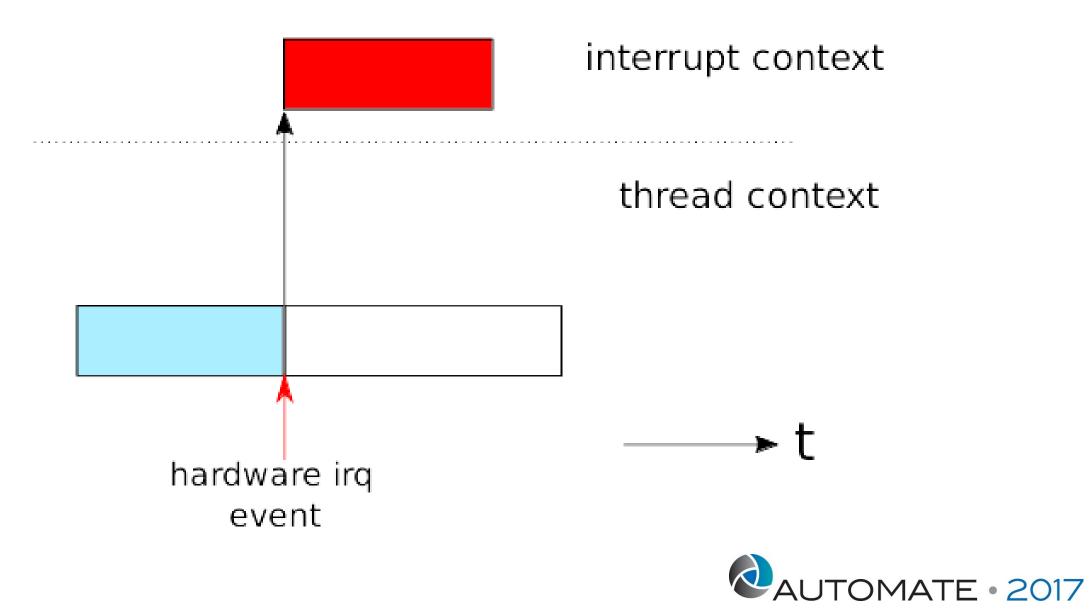
Interrupts Disabled + Spinlock



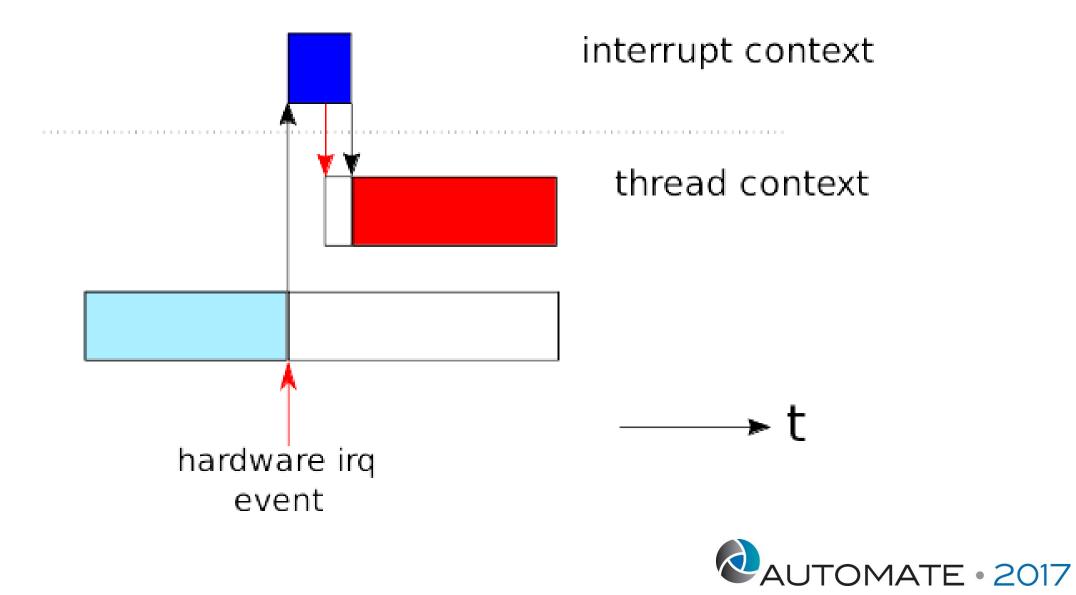




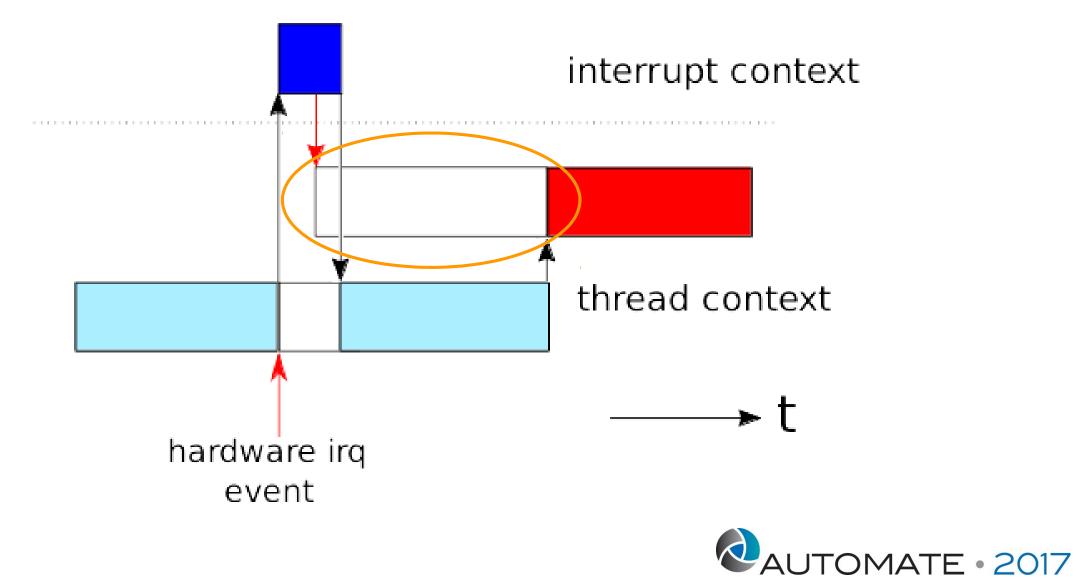
Mainline Interrupt Handling



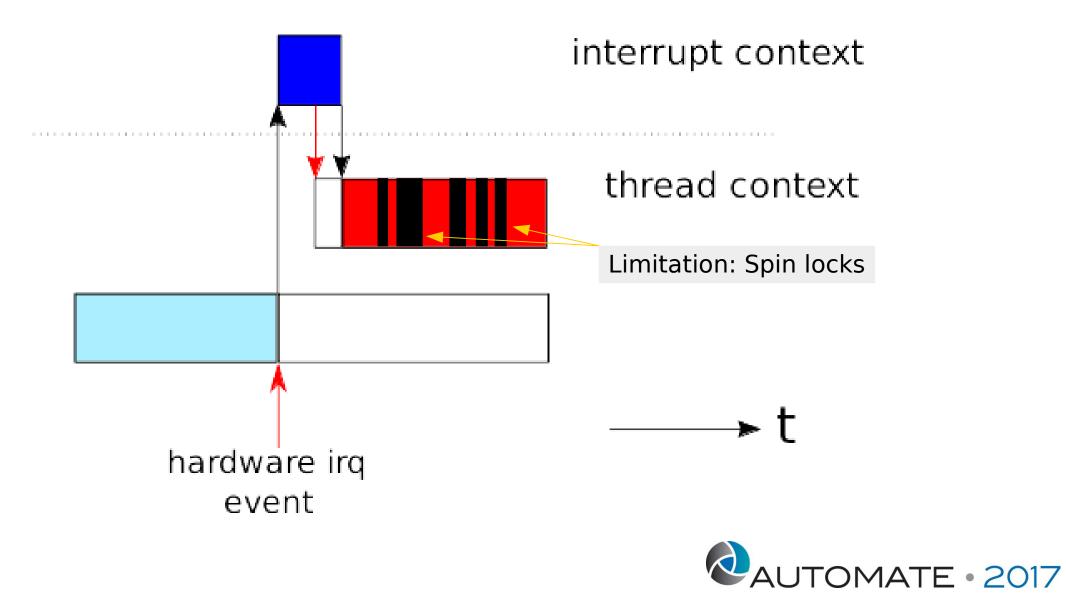
Threadirqs

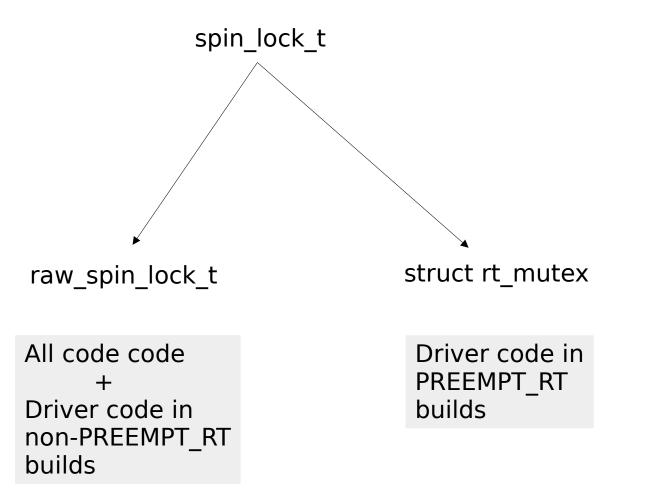


Threadirqs



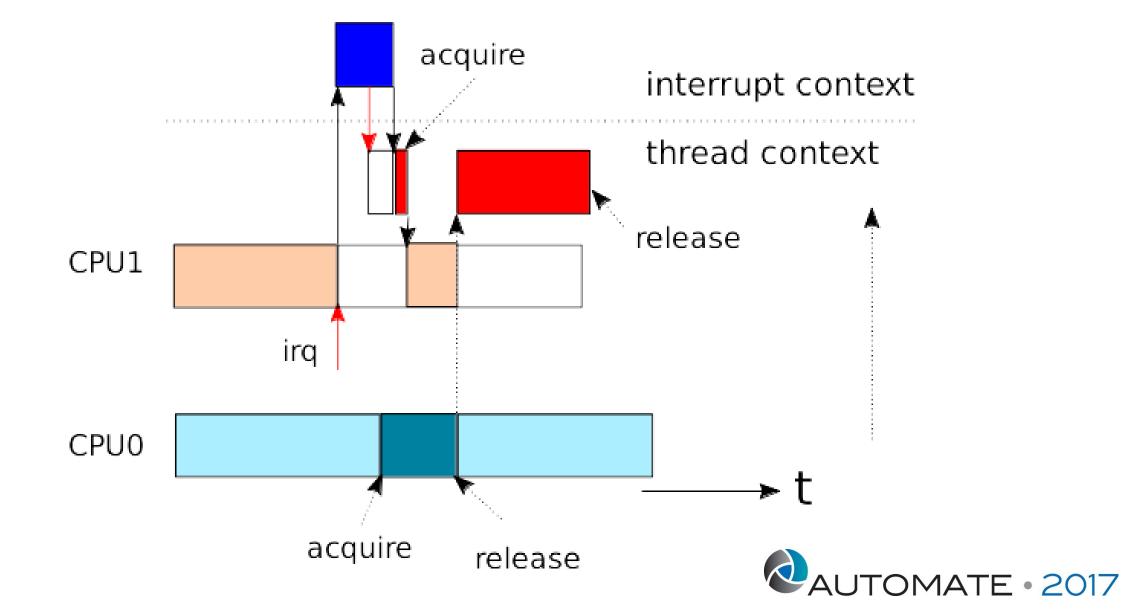
Threadirqs







Sleeping Spinlocks

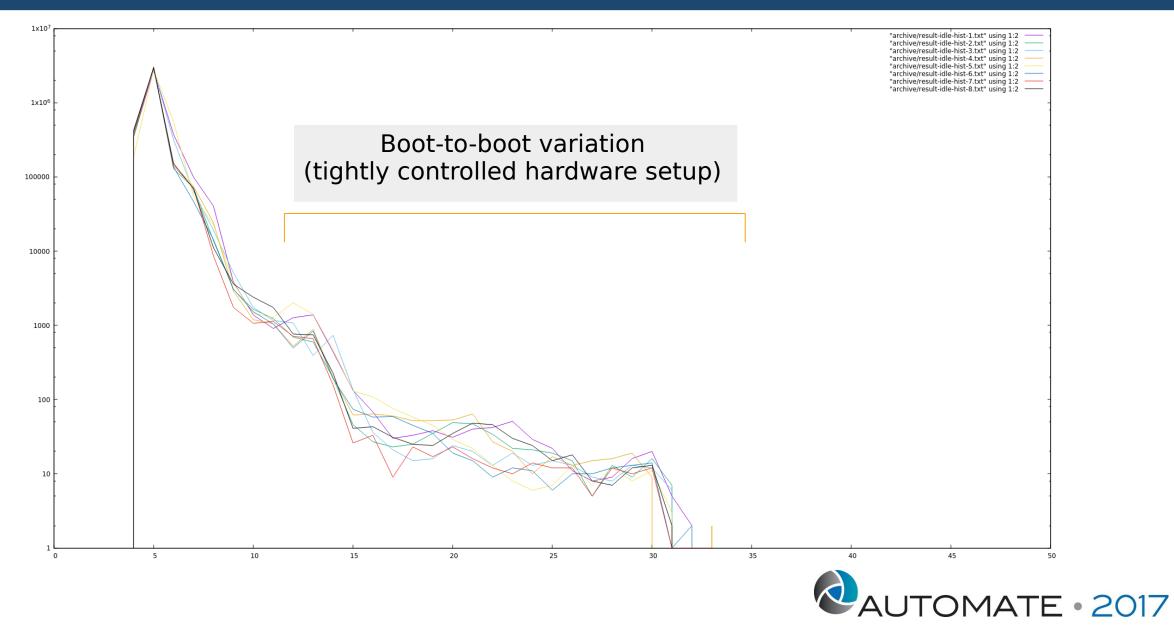


Other sources of latency (hardware):

- Cache synchronization delays
- Bus delays
- NUMA: non-uniform memory access
- Unpredictable IO events (Ethernet, WIFI)
- Temperature changes \rightarrow CPU throttling
- Etc....



Limitations



Contact Info



Haris Okanovic

Senior Software Engineer

National Instruments

11500 N. Mopac Expy. Austin, TX 78759 USA

Telephone: 1-512-683-6125 Email: haris.okanovic@ni.com

ni.com/nilinuxrt



Contact Info



Julia Cartwright

Senior Software Engineer

National Instruments

11500 N. Mopac Expy. Austin, TX 78759 USA

Telephone: 1-512-683-6620 Email: julia.cartwright@ni.com

ni.com/nilinuxrt

